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- 1. (Currently Amended) A claw-pole permanent magnet stepping motor, comprising:
 - a first case unit having a length wherein said first case unit is continuous along its length;
 - a second case unit having a length wherein said second case unit is continuous along its length;
 - said first and said second case units having a total length;
 - a rotor having at least a first and a second permanent magnet;
 - said first and said second case units having a shape supporting said rotor;
 - a third and a fourth arcuate section on each said first and said second case units:
 - a fifth and a sixth side wall section joining each respective said third and forth arcuate sections in a continuous flattened-oval section about said rotor;
 - said third and said forth arcuate sections each having a first diameter; and
 - a ratio of said total length to said first diameter is at least 1:1
 - a first metal bearing in said first case unit;
 - a second metal bearing in said second case unit;
 - said rotor supported between said first and said second metal bearings;
 - a plurality of magnetic poles on said first and second permanent magnets;
 - a first and a second phase inductor in each respective said first and said
 - second unit case opposite each respective said first and second permanent
 - magnets;
 - said first and said second phase inductors disposed symmetrically in each
 - respective said first and said second case units; and
 - said first and said second phase inductors each formed from at least a
 - first and a second magnetic plate each including multiple claw-poles and

a first and a second coil each with a set of connectors, at least one of said claw-poles facing the continuous flattened-oval section of the fifth and sixth side walls whereby said claw-pole permanent magnet stepping motor has a reduced size, eliminates magnetic circuit obstructions, and prevents external flux leakage to allow use with magnetic devices while providing an adequate rotational torque.

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- 2. (Original) A claw-pole permanent magnet stepping motor, according to claim 1, wherein: said ratio is preferably 2:1 whereby said claw-pole permanent magnet stepping motor has a reduced size while providing adequate rotational
- 3. (Cancelled)

torque despite said ratio.

- 4. (Cancelled)
- (Currently Amended) A claw-pole permanent magnet stepping motor according to claim 4, further comprising:
 - a first case unit having a length wherein said first case unit is continuous along its length;
 - a second case having a length wherein said second case unit is continuous along its length;

said first and said second case units having a total length;

a rotor having at least a first and a second permanent magnet;

said first and said second case units having a shape supporting said rotor; a third and a fourth arcuate section on each said first and said second case

units;

a fifth and a sixth side wall section joining each respective said third and fourth arcuate sections in a continuous flattened-oval section about said rotor;

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said third and said fourth arcuate sections each having a first diameter; and

a ratio of said total length to said first diameter is at least 1:1, whereby said claw-pole permanent magnet stepping motor has a reduced size, eliminates magnetic circuit obstructions, and prevents external flux leakage to allow use with magnetic devices while providing an adequate rotational torque;

said third and said fourth arcuate sections each have a first thickness; said fifth and said sixth wall sections each have a second thickness; and said first thickness being greater than said second thickness, whereby size is reduced, magnetic circuit obstructions are eliminated, and external flux leakage is minimized;

said fifth and said sixth wall sections each having a planar shape and being closer to said rotor than said third and said fourth arcuate sections; and

said at least first case unit having a flattened-oval cross section, whereby said claw-pole permanent magnet stepping motor has a reduced size; a first thin wall section on each said fifth and said sixth sections orthogonal each said third and said fourth arcuate sections; said first thin wall section having a third thickness; and said third thickness being less than said second thickness, whereby said claw-pole permanent magnet stepping motor may be made with an increased torque while retaining a same external size.

6. (Cancelled)

7. (Currently Amended) A claw-pole permanent magnet stepping motor, comprising:

a first case unit having a length wherein said first case unit is continuous along its length;

- a second case having a length wherein said second case unit is continuous along its length;
- a first and a second case unit having a total length wherein a material forming said first and second case units is magnetic;
- a rotor having at least a first and a second permanent magnet; said first and said second case units having an oval shape supporting said rotor;
- a third and a fourth arcuate section on each said first and said second case units;
- a fifth and a sixth side wall section joining each respective said third and forth arcuate sections in a continuous flattened-oval shape about said rotor;

said third and said forth arcuate sections each having a first diameter; said total length and said first diameter having a ratio of at least 1:1; said third and said fourth arcuate sections each have a first thickness; said fifth and said sixth wall sections each have a second thickness; said first thickness being greater than said second thickness; said fifth and said sixth sections each having a planar shape and being closer to said rotor than said third and said fourth arcuate sections; said at least first case unit having a flattened-oval cross section, whereby said claw-pole permanent magnet stepping motor has a reduced size, eliminates magnetic circuit obstructions, and prevents external flux leakage to allow use with magnetic devices while providing an adequate rotational torque;

- a first metal bearing in said first case unit;
- a second metal bearing in said second case unit;
- said rotor supported between said first and said second metal bearings;
- a plurality of magnetic poles on said first and second permanent magnets;
- a first and a second phase inductor in each respective said first and said

second unit case opposite each respective said first and second permanent magnet;

said first and said second phase inductors disposed symmetrically in each respective said first and said case units; and said first and said second phase inductors each formed from at least a first and a second magnetic plate each having multiple claw-poles and a first and a second coil each with a set of connectors, at least one of said

claw-poles facing the continuous flattened-oval section of the fifth and sixth side walls, whereby said adequate rotational torque is created.

8. (Original) A claw-pole permanent magnet stepping motor, according to claim 7, wherein:
said ratio is preferably 2:1.

- 9. (Currently Amended) A claw-pole permanent magnet stepping motor, comprising:
 - a first case unit having a length wherein said first case unit is continuous along its length;
 - a second case having a length wherein said second case unit is continuous along its length;

said first case unit and said second case unit having a first total length wherein a material forming said first and second case units is magnetic; a rotor including a first and a second permanent magnet; said first and said second case units having an oval shape which comprises an arcuate section and a flattened-oval section supporting said rotor;

a permanent magnet magnetized to form a plurality of poles; said permanent magnet on said rotor;

a first phase inductor;

a second phase inductor;

said first and said second phase inductors disposed symmetrically in each respective said case unit; said first and said second phase inductors each including at least a plurality of claw poles and a coil at least one of said claw-poles facing the continuous flattened-oval section of the case units; said first and said second case units having a first diameter; and a ratio of said first total length to said first diameter is at least 1:1, whereby said claw-pole permanent magnet stepping motor has a reduced size, eliminates magnetic circuit obstructions, and prevents external flux leakage to allow use with magnetic devices while providing an adequate rotational torque.

- 10. (Original) A claw-pole permanent magnet stepping motor, according to claim 9, wherein: said ratio is preferably 2:1, whereby said adequate rotational torque is maintained.
- 11. (Original) A claw-pole permanent magnet stepping motor, according to claim 10, further comprising:

 a securing section detachably attached to an outside side surface of at least one of said first and said second case unit;

 a securing section containing an externally threaded section; and said securing section being detatachably fixable to an external attachment base for said claw-pole permanent magnet stepping motor, whereby said claw-pole permanent magnet stepping motor may be easily affixed to an external device.
- 12. (Previously Presented) A claw-pole permanent magnet stepping motor, according to claim 11 wherein:each said first and said second phase inductor includes said coil and a

magnetic plate formed integrally from a magnetic material; each said magnetic plate having an oval shape, including a flat oval-shaped section and an extending plurality of claw-poles, for sliding insertion in each respective said first and said second case unit, whereby assembly time is reduced and efficiency increased.

13. (Original) A claw-pole permanent magnet stepping motor, according to claim 12, wherein:

each said coil includes a coil bobbin; an insulated copper wire wrapped around said coil bobbin, and a connector;

said coil bobbin including a first and a second collar;

said connector disposed at at least one of said first and said second collar orthogonal to said coil; and

said coil bobbin having a flat oval shape with arcuate sections, whereby said coils are quickly install-able inside each respective said first and said second case units.